

## 3-Phase DC Fan Driver

### Features

- Sinusoidal drive for low audible noise
- High efficiency control algorithm
- Sensorless/1-hall operation
- PWM speed control
- Adjustable Speed curve
- SO speed output
- Lock protection
- Over current protection
- Soft-start
- TQFN4X4-24 (R5) packages

### General Description

M8320 is designed for 3 phase motor control, driven by sensorless method or one hall. It includes 180° sinusoidal driving algorithm for low audible noise. M8320 is available in TQFN4X4-24 (R5) packages.

### Applications

- Notebook

### Ordering Information

ORDER NUMBER	MARKING	TEMP. RANGE	PACKAGE (Green)
M8320R51U	8320	-40°C to +125°C	TQFN4X4-24

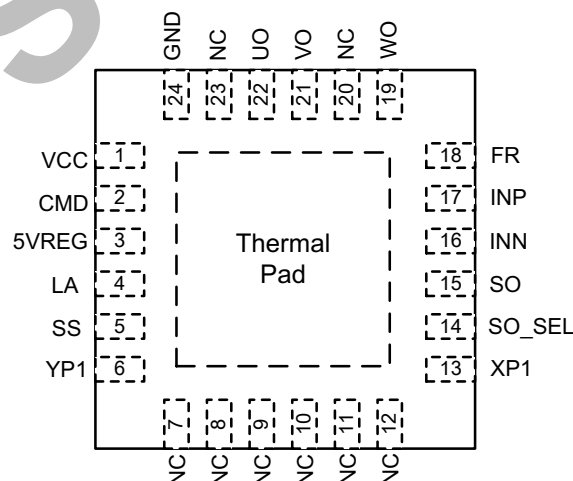
Note: R5: TQFN4X4-24

1: Bonding Code

U: Tape & Reel

Green: Lead Free / Halogen Free

### Pin Configuration



**TQFN4X4-24**

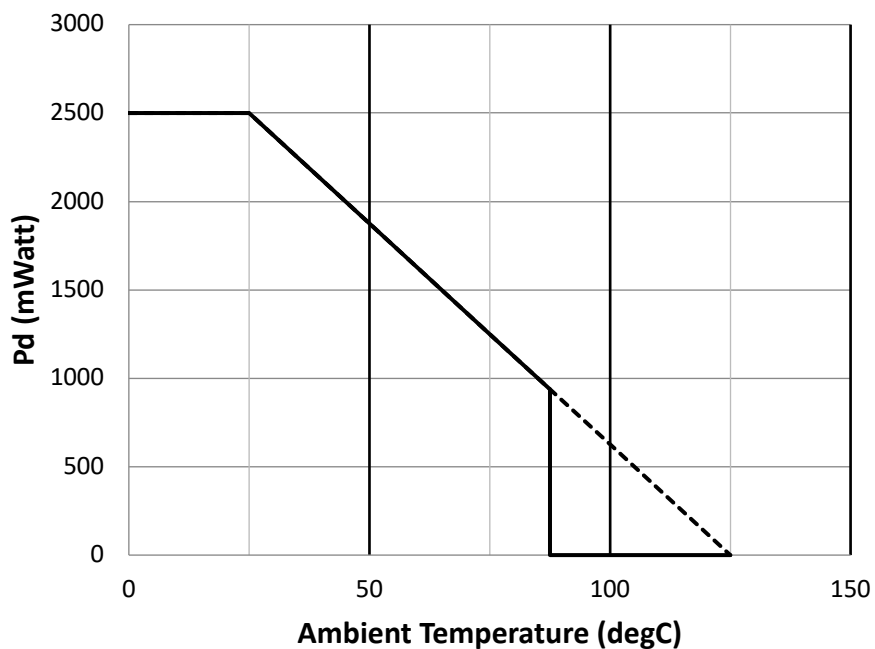
Note: Recommend connecting the Thermal Pad to the Ground for excellent power dissipation.

## Absolute Maximum Ratings

VCC to GND Max Voltage. . . . . -0.3V to 18V  
 VCC to GND Peak Voltage under 100nS . . . . . 26V  
 5VREG to GND . . . . . -0.3V to 7V  
 UO, VO, WO Output Peak current . . . . . 2.16A  
 UO, VO, WO Output Voltage . . . . . -0.3V to VCC  
 SO Output Voltage . . . . . -0.3V to VCC  
 SO Output Current . . . . . 10mA  
 CMD to GND . . . . . -0.3V to VCC  
 LA, SS, XP1, YP1, SO\_SEL Pin to GND . . -0.3V to 7V  
 INP, INN to GND . . . . . -0.3V to 7V  
 FR to GND . . . . . -0.3V to VCC

Thermal Resistance of Junction to Ambient ( $\theta_{Jc}$ )  
 TQFN4X4-24 . . . . . 20°C/W  
 Continuous Power Dissipation ( $T_A=25^\circ\text{C}$ )  
 TQFN4X4-24 . . . . . 2.5W  
 Operating Temperature Range . . . . -40°C to +125°C  
 Junction Temperature . . . . . +150°C  
 Storage Temperature Range . . . . . -65°C to +150°C  
 Reflow Temperature (soldering, 10sec) . . . . 260°C  
 ESD (HBM) . . . . . 4KV  
 ESD (MM) . . . . . 400V

## TQFN4X4-24Pin Thermal Derating Curve



Note : When glass epoxy board (double layer) of 35mmx35mmX1.2mm is mounted.

## Electrical Characteristics

( $V_{IN}=12V$ ;  $T_A = T_J = 25^{\circ}C$ .)

The device is not guaranteed to function outside its operating conditions. Parameters with MIN and/or MAX limits are 100% tested at  $+25^{\circ}C$ , unless otherwise specified.

PARAMETER	SYMBOL	CONDITION	MIN	TYP	MAX	UNIT
<b>V<sub>IN</sub></b>						
Input Voltage	V <sub>DD</sub>		4.5	12	18	V
Operating Current	I <sub>Q</sub>		2.5	3	3.5	mA
Standby Current	I <sub>SB</sub>	V <sub>CMD</sub> = 0V	200	---	400	μA
Power ON delay Time	T <sub>td</sub>	V <sub>CC</sub> = 0 V to 12V	153.6	192	230.4	mS
<b>PWM mode</b>						
CMD Input Low Voltage	V <sub>CMDL</sub>		0	---	0.8	V
CMD Input High Voltage	V <sub>CMDH</sub>		2	---	V <sub>CC</sub>	V
CMD Pull High Current	I <sub>CMD</sub>	V <sub>CMD</sub> = 0V	160	200	240	μA
PWM Input Frequency	F <sub>PWM</sub>		0.1	---	50	kHz
Output Switch Frequency	F <sub>OUT</sub>		50	62.5	75	kHz
<b>Internal Regulator</b>						
5V Regulator Output Voltage	V <sub>5VREG</sub>	I <sub>5VREG</sub> = -10mA	4.9	5	5.1	V
5V Regulator Current Limit	I <sub>5VOC</sub>		15	60	70	mA
<b>Output Drivers</b>						
High-side Output Voltage	V <sub>OH</sub>	V <sub>CC</sub> = 12V, I <sub>OUT</sub> = 400mA		0.22		V
Low-side Output Voltage	V <sub>OL</sub>	V <sub>CC</sub> = 12V, I <sub>OUT</sub> = 400mA		0.14		V
SO Low Voltage	V <sub>SOL</sub>	I <sub>SO</sub> = 5mA	0.2		0.3	V
SO Off Leakage Current	I <sub>SOL</sub>	V <sub>SO</sub> = 12V	---	---	1	μA
<b>Soft Start Oscillator</b>						
SS High Voltage	V <sub>SSH</sub>		1	1.2	1.4	V
SS Low Voltage	V <sub>SSL</sub>		0.5	0.6	0.7	V
SS Charge Current	I <sub>SS1</sub>	V <sub>SS</sub> = 0V	8	10	12	μA
SS Discharge Current	I <sub>SS2</sub>	V <sub>SS</sub> = 2V	8	10	12	μA
<b>FR</b>						
FR Input Low Voltage	V <sub>FRL</sub>		0	---	0.8	V
FR Input High Voltage	V <sub>FRH</sub>		2	---	V <sub>CC</sub>	V
FR Pull Low Resistor	R <sub>FR</sub>		100	120	140	kΩ
<b>HALL</b>						
INP Input Pull High Current	I <sub>INP</sub>		5	8	15	μA
INN Input Pull High Current	I <sub>INN</sub>		5	8	15	μA
HALL Input Hysteresis	V <sub>HALL</sub>		5	12.5	20	mV
<b>RPM</b>						
Max RPM	R_limit	2 pair pole (4P)	25000	31250	---	rpm

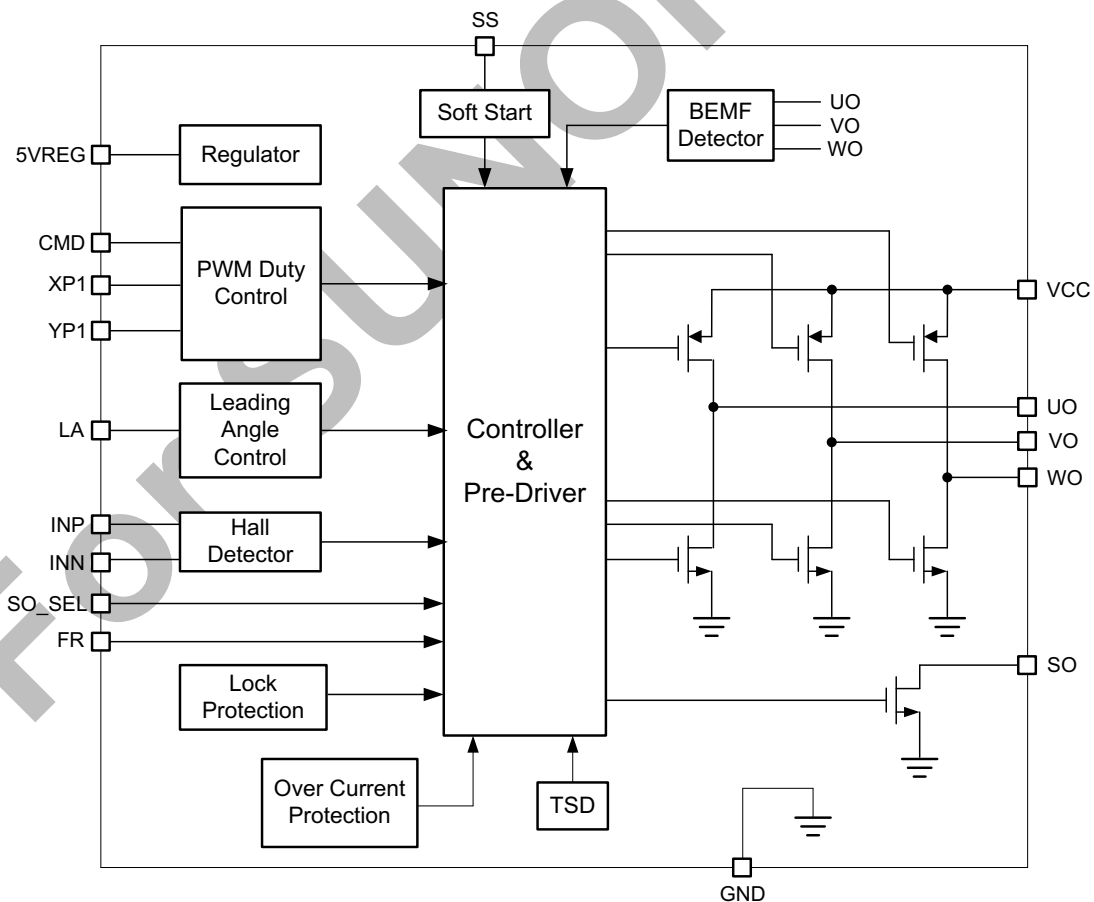
## Electrical Characteristics (Continued)

PARAMETER	SYMBOL	CONDITION	MIN	TYP	MAX	UNIT
<b>Current Protection</b>						
Current Limit level	$I_{LIM}$	$V_{SS} = 0V$ , Start-up	0.32	0.4	0.48	A
Current Limit level	$I_{LIM}$	Normal	0.96	1.2	1.44	A
Over current protection level	$I_{OC}$		1.44	1.8	2.16	A
<b>Lock Protection</b>						
Re-start Time *	$T_{on\_S}$	Soft Start $LA > 2.5V$	0.8	1	1.2	Sec
Re-start Time *	$T_{on\_F}$	Full Duty $LA < 2.5V$	1.2	1.25	1.5	Sec
Lock Mode Time	$T_{off}$		4	5	6	Sec
Lock Mode Time 1st	$T_{off\_1st}$		0.8	1	1.2	Sec
On/Off Ratio			---	5	---	---
<b>Thermal Protection</b>						
Thermal Protection Temp.	$T_{TSD}$		155		175	°C
Thermal Protection Hysteresis	$T_{HYS}$		---	30	---	°C
<b>Vzc Comparator</b>						
Vzc Hysteresis Voltage Com to Output	$V_{zc\_ST}$	Soft Start UP ( $V_{CC} > 9V$ )	---	---	140	mV
Vzc Hysteresis Voltage Com to Output	$V_{zc}$	Soft Start UP ( $V_{CC} < 7.5V$ ) or Normal running or Full duty	---	---	50	mV

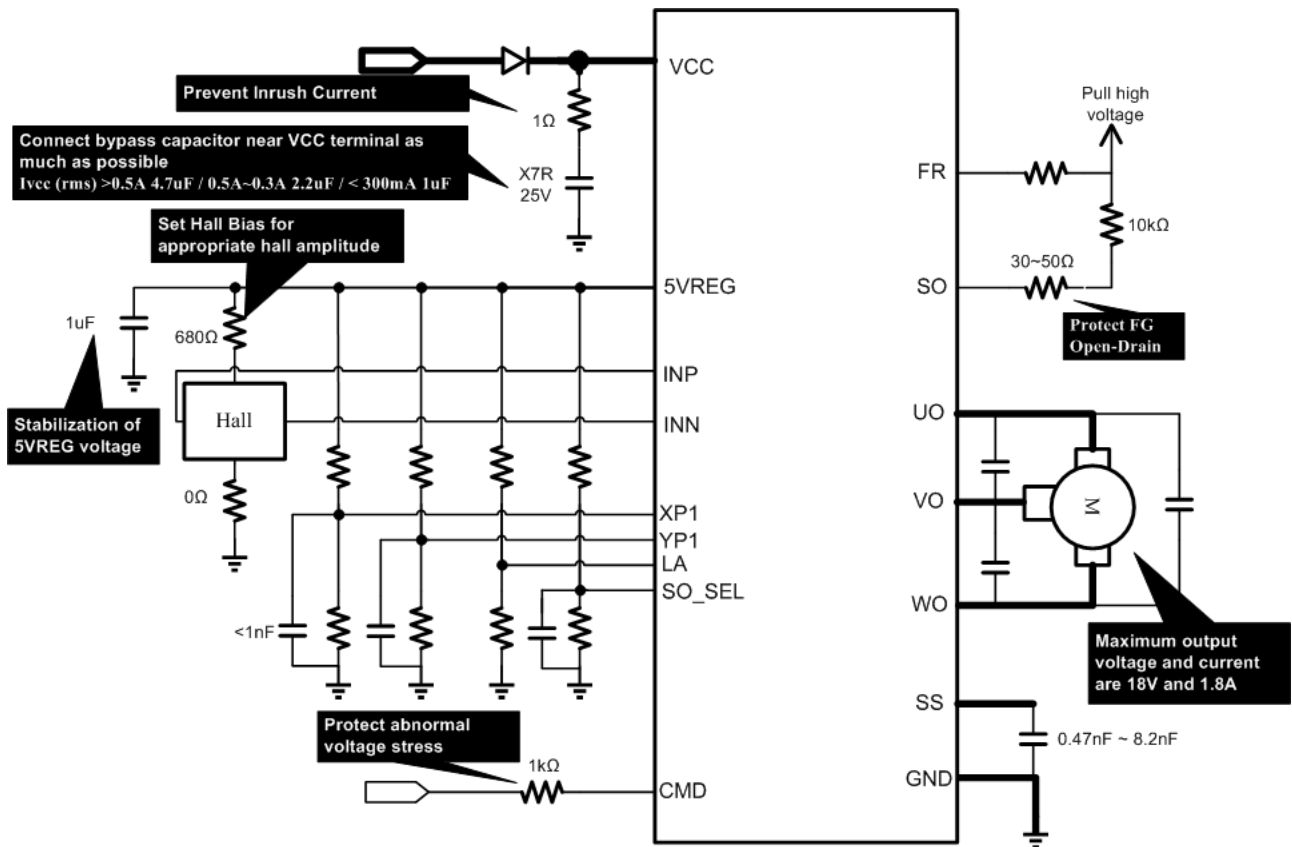
\*Note : Lock ON Time = Duty 0% ~ 50% time +  $T_{on\_S}$  / Detail see page 11 waveform

**Pin Description**

PIN NO.	SYMBOL	DESCRIPTION
1	VCC	Input Supply
2	CMD	Speed Control
3	5VREG	5V Regulator Output
4	LA	Leading Angle Setting
5	SS	Soft-Start Time Setting
6	YP1	Minimum Output PWM Duty Setting
7,8,9,10,11,12,20,23	NC	No Connection
13	XP1	Minimum Input PWM Duty Setting
14	SO_SEL	SO Mode Setting
15	SO	Rotation Speed/Detection Output
16	INN	Hall - input terminal
17	INP	Hall + input terminal
18	FR	Rotation Direction Control
19	WO	Motor Terminal W
21	VO	Motor Terminal V
22	UO	Motor Terminal U
24	GND	Ground

**Block Diagram**


**Application Circuit Examples**



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## Function Descriptions

### Speed Control Setting

The XP1 / YP1 is detected by ADC which has 256 steps, and the resolution is 15.625mV/step. As a result, the ADC can detect voltage from 0.5V(ADC=0) to 4.5V(ADC=255).

(A) The XP1 pin is a multi function pin setting by voltage from 0V ~ 5V. The main function controls the turning point of input low duty at speed curve. The second function is to set speed curve with shutdown or minimum speed.

Equation :

$$D_{XP1} = \frac{V_{IN}}{15.625mV} \times \frac{100\%}{255}$$

$$V_{XP1} > 2.5V, V_{IN} = 4.5V - V_{XP1}$$

$$V_{XP1} < 2.5V, V_{IN} = V_{XP1} - 0.5V$$

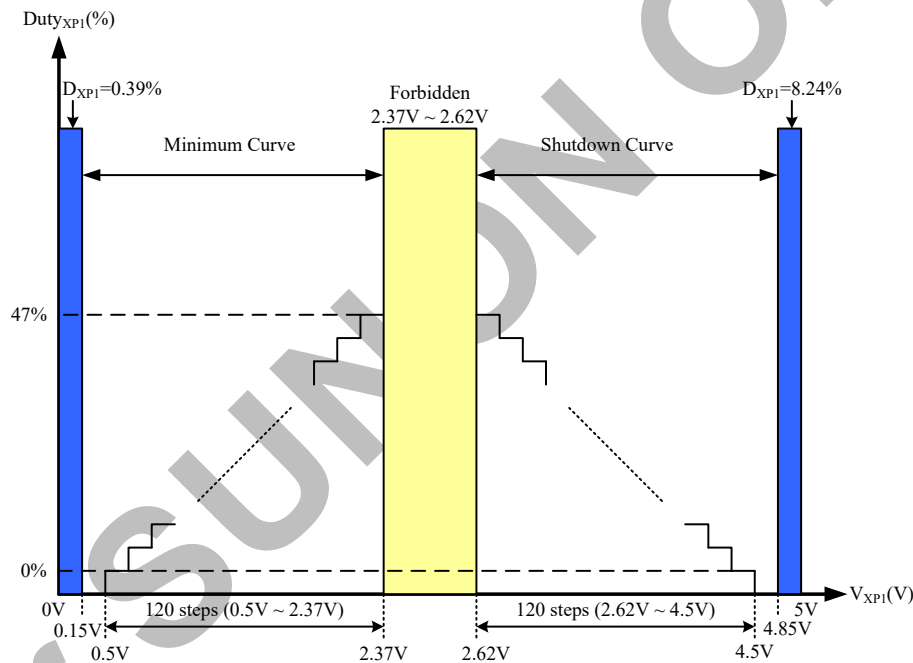


Figure 1. XP1 Voltage Setting Range

Step	V <sub>XP1</sub> (V)	XP1 duty (%)	Sec. Function
	>4.85	8.24	Shutdown
255	4.5	0	
136	2.62	47	
Forbidden			
120	2.37	47	Minimum
0	0.5	0	
	<0.15	0.39	

(B) The YP1 pin is a multi function pin setting by voltage from 0V ~ 5V. The main function controls the turning point of output low duty at speed curve. The second function is to set CMD pin with PWM or VSP speed control. When VSP control, CMD pin 0.5V ~ 4.5V means input PWM duty 0% ~ 100%.

Equation :

$$D_{YP1} = \frac{V_{IN}}{15.625mV} \times \frac{100\%}{255}$$

$$V_{YP1} > 2.5V, V_{IN} = 4.5V - V_{YP1}$$

$$V_{YP1} < 2.5V, V_{IN} = V_{YP1} - 0.5V$$

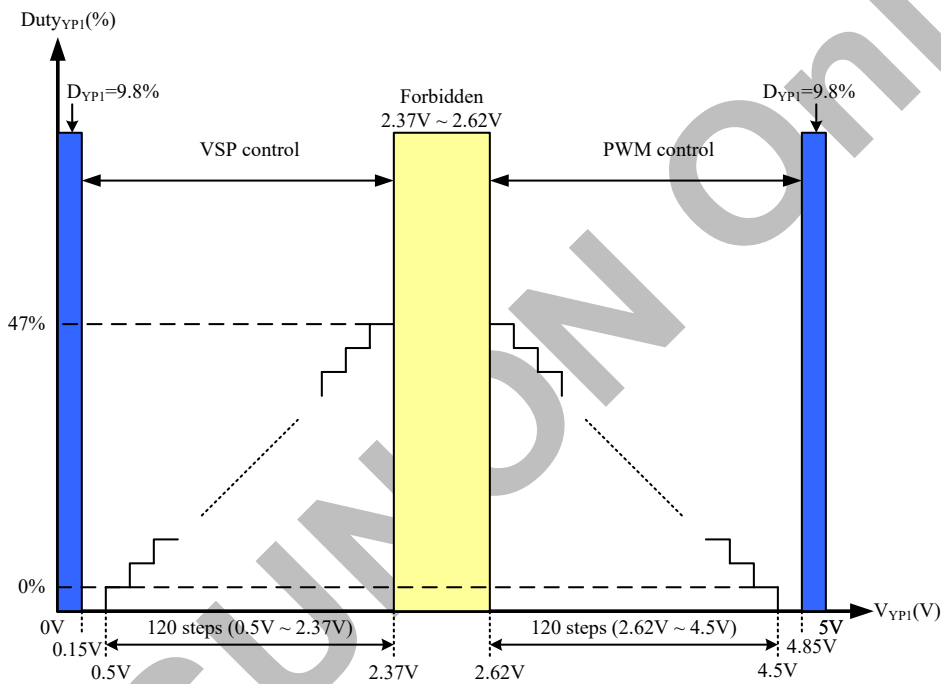


Figure 2. YP1 Voltage Setting Range

Step	VYP1 (V)	Duty output (%)	Sec. Function
	>4.85	9.8	PWM control
255	4.5	0	
136	2.62	47	
Forbidden			
120	2.37	47	VSP control
0	0.5	0	
	<0.15	9.8	

**Phase Control Setting**

The LA pin is a multi function pin setting by voltage from 0V ~ 5V. The main function controls the leading angle based on commutation signal. If LA pin is 0V or 5V, the leading angle is controlled automatically for high efficiency. The second function is to set soft-start or full duty start-up.

Equation :

$$P_{LA} = \left( \frac{V_{IN}}{62.5mV} \right) \times \frac{29^\circ}{31} + 7.5^\circ$$

$$V_{LA} > 2.5V, V_{IN} = 4.5V - V_{LA}$$

$$V_{LA} < 2.5V, V_{IN} = V_{LA} - 0.5V$$

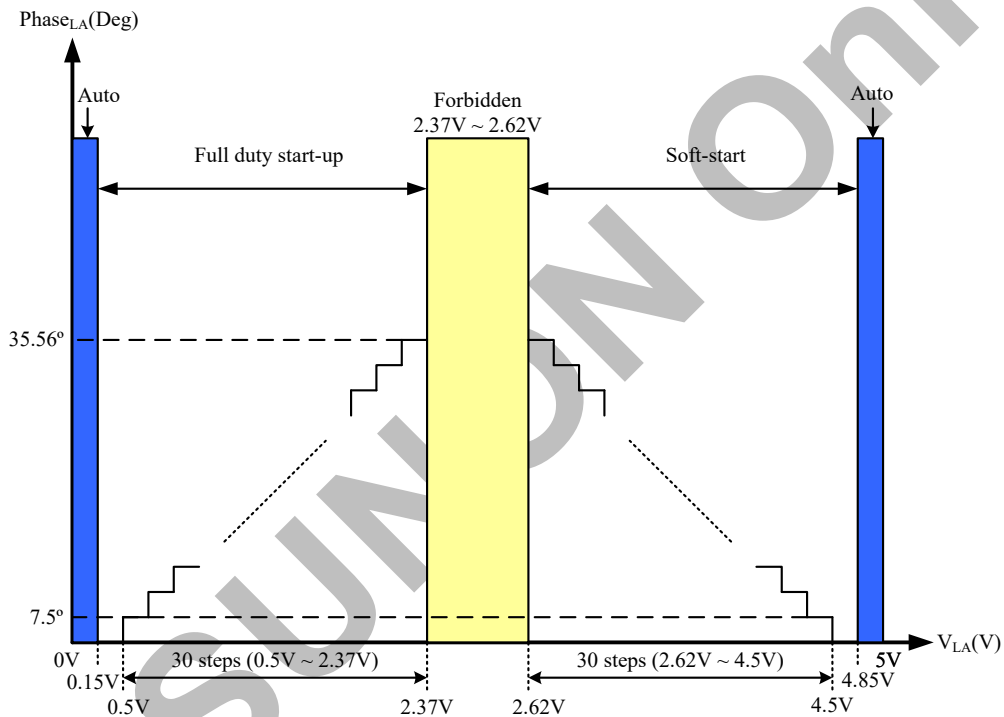


Figure 3. LA Voltage Setting Range

Step	V <sub>LA</sub> (V)	LA (Deg)	Sec. Function
	>4.85	Auto	Soft-start
255	4.5	7.5	
136	2.62	35.56	
Forbidden			
120	2.37	35.56	Full duty start-up
0	0.5	7.5	
	<0.15	Auto	

**SO SEL Table**

The M8320 supports FG、1/2FG、1/3FG、2FG and RD outputs.

SO_SEL Pin Input Voltage	SO Output
5V	FG
3.5V	1/2FG
2.5V	2FG
1.5V	1/3FG
0V	RD

**Sensor less and 1-hall operation**

The M8320 provides sensor less and 1-hall driving algorithm. At 1-hall mode, it supports both hall element and hall sensor applications. If the pins INP and INN keep floating or GND, the M8320 will switch to sensor less mode.

**Current Limit**

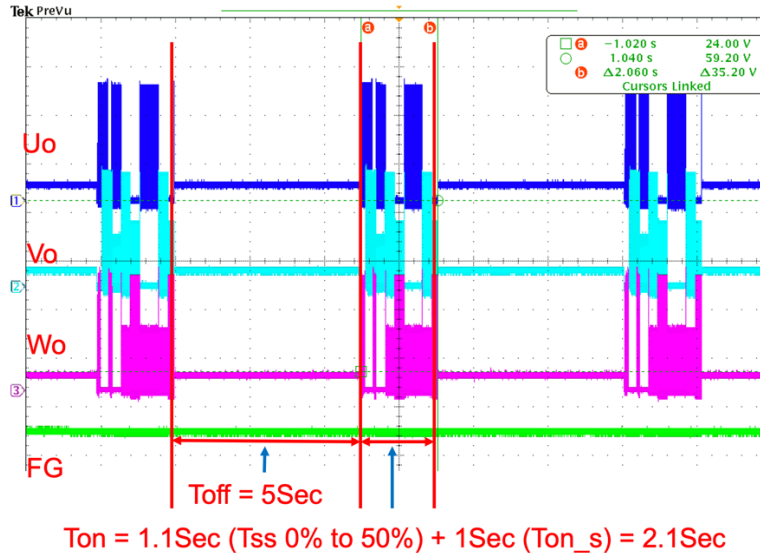
The M8320 includes internal current limit. It will turn off high side PMOS when output driver current is over 1.2A. The high side PMOS will turn on at next PWM cycle, and reduce the output duty. The M8320 also includes over current protection (OCP). If the output driver current is over 1.8A, all output MOS will turn off and enable lock protection. Chip will restart when lock off time is count down.

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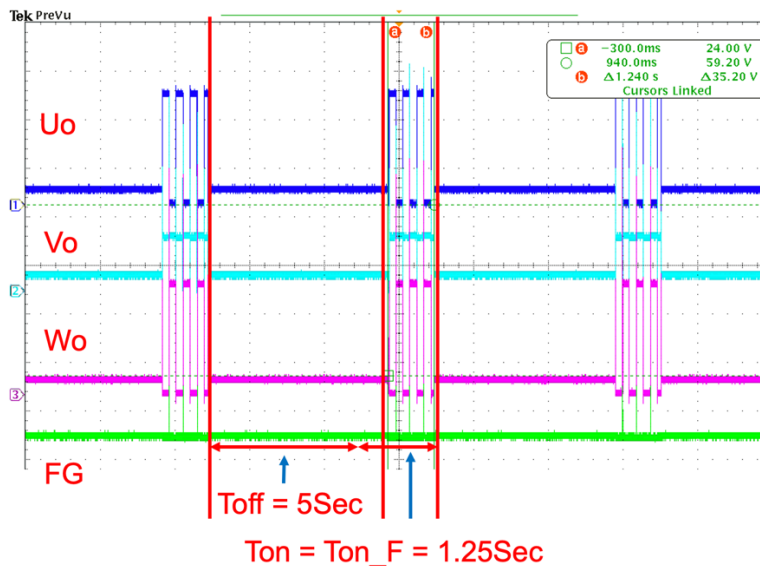
## Lock Protection and Automatic Restart

The M8320 provides the lockup protection and automatic restart function for preventing the motor coil burns out. If the motor cannot start-up successfully, this chip internal clock will count an on time 1s ( $T_{ON}$ ). Then all driver MOSFETs are turned off and auto restart after the recovery time ( $T_{OFF}$ ). The first recovery time is 1s and the others are 5s.

Vcc=12V C<sub>ss</sub>=2.2nF LA=5V (Soft Start) Lock Restart



Vcc=12V C<sub>ss</sub>=2.2nF LA=0V (Full Duty) Lock Restart



## Quick Start and Standby Mode

When the input PWM duty of CMD pin is below XP1 duty with shutdown function, the lock protection signal will be disable. Chip all circuit still work except driver MOSFETs turned off, and wait for quick start by the control signal. The M8320 also has standby mode enabled by the control signal under low duty (<0.5%) over a fixed time (16ms). In the standby mode, it will turn off all driver MOSFETs, internal clock and SO function, and the quiescent current is under 400 $\mu$ A.

## SS Capacitor Setup

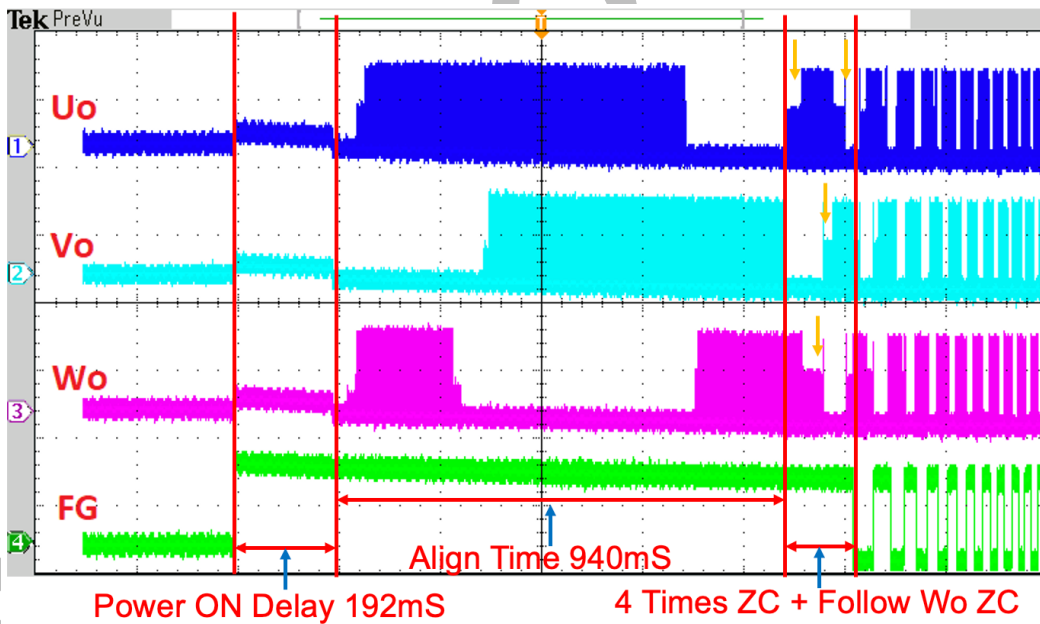
The SS capacitor is used to set output duty changing rate for soft-start and normal operation. The time of the output duty changing from 0% to 100% is 1s when the capacitor is 1nF. The proper capacitor value is obtained by experiments.

C <sub>ss</sub>	SS time 0% to 100%	Align time _ Typical (V <sub>cc</sub> > 8.5V)	Align time _ Typical (V <sub>cc</sub> < 7.5V)	SC time _ Typical
1nF	1Sec	0.2Sec	0.3Sec	250mS
2.2nF	2.2Sec	0.44Sec	0.66Sec	250mS
3.3nF	3.3Sec	0.66Sec	0.99Sec	250mS
4.7nF	4.7Sec	0.96Sec	1.41Sec	250mS
5.6nF	5.6Sec	1.12Sec	1.68Sec	250mS
6.8nF	6.8Sec	1.36Sec	2.04Sec	250mS

Note : Align time & Soft Start time & SC time with +/- 20% tolerance

## Soft Start UP

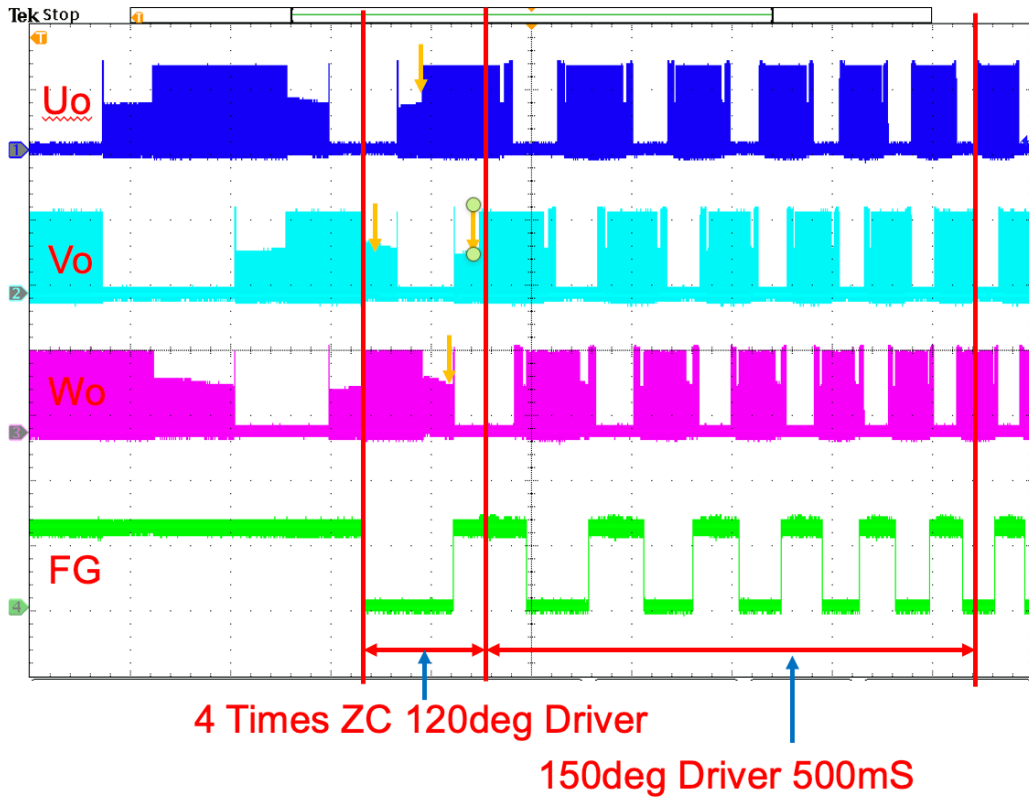
Start UP Waveform Vin = 12V C<sub>ss</sub> = 4.7nF



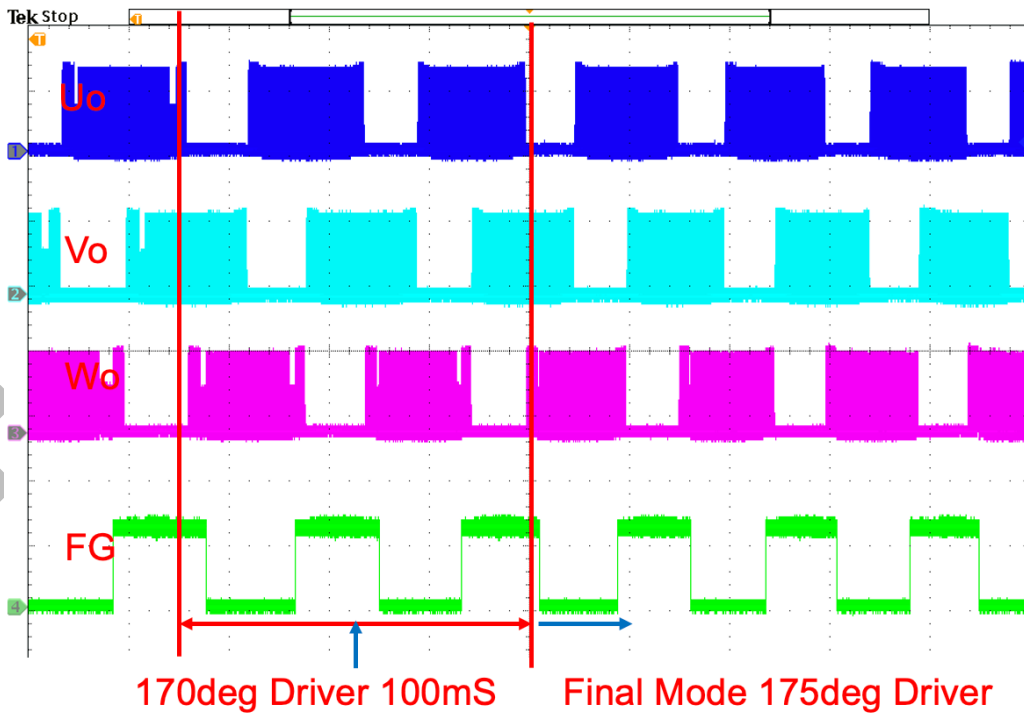
Note : FG out Time = Power ON Delay + Align Time + 4 Time ZC Follow Wo ZC

Start UP Transition Mode Driver :

Transition Mode 120deg Driver to 150deg Driver



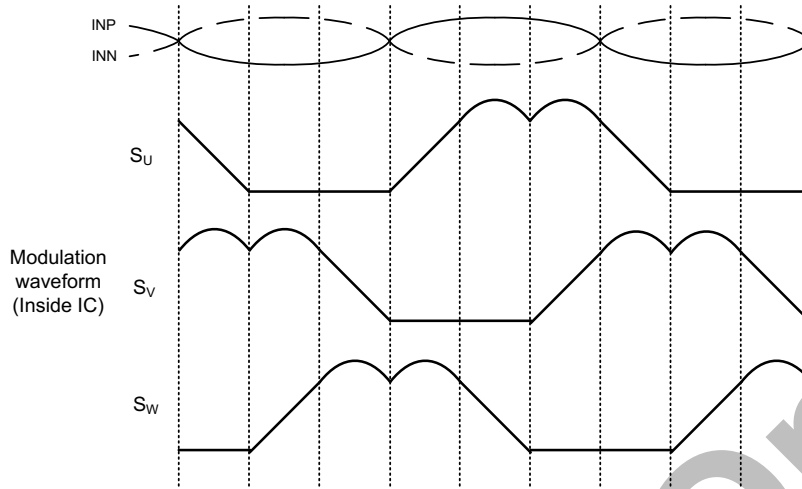
Transition Mode 170deg Driver to 175deg Driver



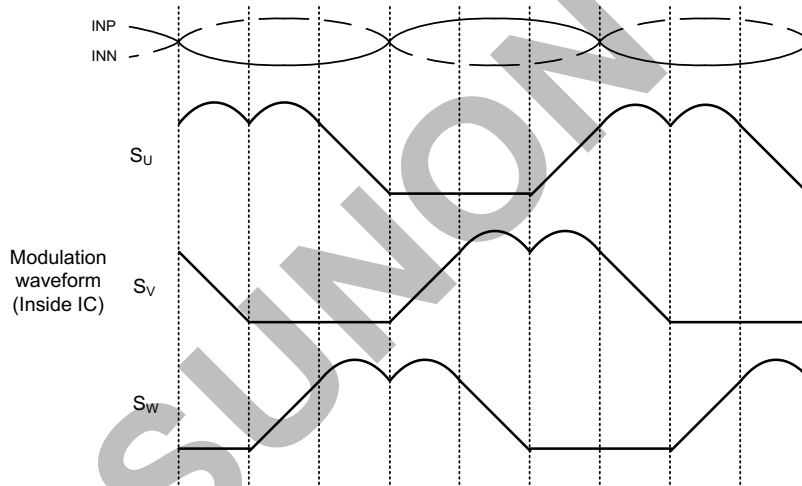
Note : FG out + 4ZC 120deg Driver + 150deg Driver 0.5sec + 170deg Driver 0.1Sec >> Final mode 175deg Driver

**One Hall Driver**

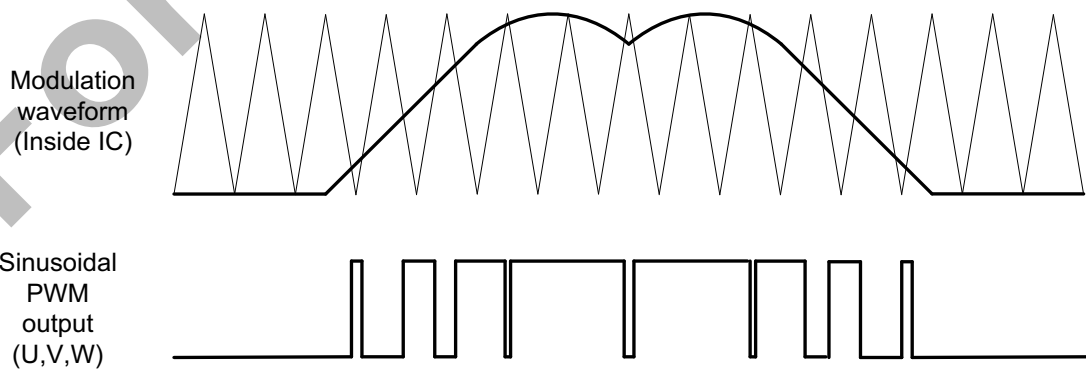
**Forward Rotation Timing Chart (FR = 5VREG)**



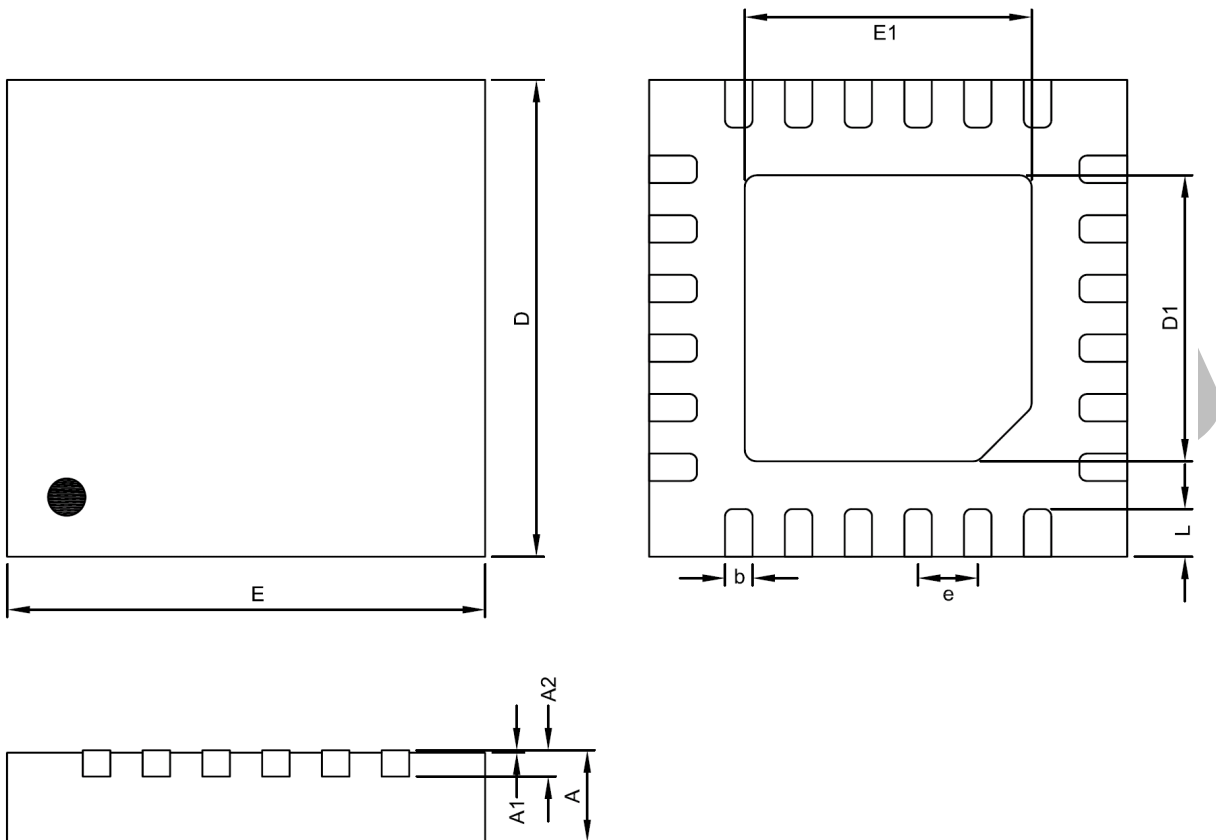
**Reverse Rotation Timing Chart (FR = 0V)**



**Sine-Wave PWM Output**



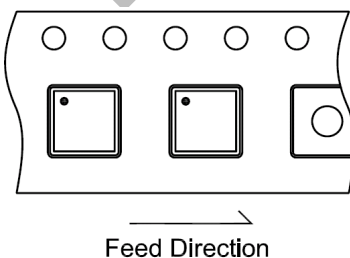
## Package Information



TQFN4X4-24 Package

Symbol	DIMENSION IN MM			DIMENSION IN INCH		
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
A	0.70	0.75	0.80	0.0276	0.0295	0.0315
A1	0.00	---	0.05	0.0000	---	0.0020
A2	0.20 REF			0.0079 REF		
D	3.95	4.00	4.05	0.1555	0.1575	0.1594
E	3.95	4.00	4.05	0.1555	0.1575	0.1594
D1	2.50	2.70	2.85	0.0984	0.1063	0.1122
E1	2.50	2.70	2.85	0.0984	0.1063	0.1122
b	0.18	0.23	0.30	0.0071	0.0091	0.0118
e	0.50 BSC			0.0197 BSC		
L	0.35	0.40	0.45	0.0118	0.0138	0.0177

## Taping Specification



PACKAGE	Q'TY/BY REEL
TQFN4X4-24	3,000 ea

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